

said mobile body estimated by said mobile body position estimator based on absolute position information of said mobile body.

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7. (Amended) A mobile body controller as claimed in Claim 1, wherein the initial value of the position of said mobile body estimated by said mobile body position estimator is set based on the absolute position information of said mobile body.

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Please add new claims 14-16 as follows:

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--14. (new) A mobile body controller as claimed in Claim 2, further comprising a mobile body position indicator which displays the position of said mobile body estimated by said mobile body position estimator.

15. (new) A mobile body controller as claimed in Claim 2, further comprising position information correcting means which corrects the position of said mobile body estimated by said mobile body position estimator based on absolute position information of said mobile body.

16. (new) A mobile body controller as claimed in Claim 2, wherein the initial value of the position of said mobile body estimated by said mobile body position estimator is set based on the absolute position information of said mobile body.--
